

ABSTRACT AND REFERENCES

MATHEMATICS AND CYBERNETICS – APPLIED ASPECTS

DOI: 10.15587/1729-4061.2017.95157

**DEVELOPMENT OF A MATHEMATICAL MODEL
FOR PREDICTING POSTOPERATIVE PAIN
AMONG PATIENTS WITH LIMB INJURIES
(p. 4-9)**

Marine Georgiyants

Kharkiv Medical Academy of
Postgraduate Education, Kharkiv, Ukraine
ORCID: <http://orcid.org/0000-0002-1373-7840>

Oleksandr Khvysyuk

Kharkiv Medical Academy of
Postgraduate Education, Kharkiv, Ukraine

Nataliya Boguslavska

Kharkiv Regional Clinical
Traumatological Hospital, Kharkiv, Ukraine

Olena Vysotska

Kharkiv National University of
Radio Electronics, Kharkiv, Ukraine
ORCID: <http://orcid.org/0000-0003-3723-9771>

Anna Pecherska

Kharkiv National University of
Radio Electronics, Kharkiv, Ukraine
ORCID: <http://orcid.org/0000-0001-7069-0674>

A mathematical model is devised to predict the probability of development of postoperative pain among patients of young age, operated on in a planned manner for the limb injuries. As the model predictors we selected: the level of pain before operation, determined by the visual analog scale, result of evaluation of cognitive abilities by the Montreal scale and level of the mean blood pressure. The application of the developed model makes it possible to improve quality of providing the patients with anaesthesiological assistance. The results obtained might be used in the development of information decision support system for a physician-anaesthesiologist for the objectification and automation of the process for determining the probability of development of postoperative pain syndrome. The introduction of such a system into clinical practice will make it possible to reduce the load on the medical staff and decrease the amount of anaesthetising preparations for patients, whose value of the level of pain before operation, determined by the visual analog scale after the operation, does not exceed 3 points, as well as to conduct more adequate analgesia among patients with a higher value of this indicator.

Keywords: postoperative pain, limb injury, patients of young age, anesthesia, prediction, logistic regression.

References

1. Gerbershagen, H. J., Dagtekin, O., Rothe, T., Heidenreich, A., Gerbershagen, K., Sabatowski, R. et. al. (2009). Risk factors for acute and chronic postoperative pain in patients with benign and malignant renal disease after nephrectomy. European Journal of Pain, 13 (8), 853–860. doi: 10.1016/j.ejpain.2008.10.001
2. White, P. F., Kehlet, H. (2010). Improving Postoperative Pain Management. Anesthesiology, 112 (1), 220–225. doi: 10.1097/ala.0b013e3181c6316e
3. Ovechkin, A. M. (2015). Postoperative pain: the state of problem and current trends in postoperative analgesia. Rehionarnaia anestesiia i lechenie ostroj boli, 9 (2), 29–39.
4. Breivik, H., Borchgrevink, P. C., Allen, S. M., Rosseland, L. A., Romundstad, L., Breivik Hals, E. K. et. al. (2008). Assessment of pain. British Journal of Anaesthesia, 101 (1), 17–24. doi: 10.1093/bja/aen103
5. Salaffi, F., Ciapetti, A., Carotti, M. (2012). Pain assessment strategies in patients with musculoskeletal conditions. Reumatismo, 64 (4). doi: 10.4081/reumatismo.2012.216
6. El'skij, V. N., Zyablicev, S. V., Pishchulina, S. V., Kisheňya, M. S., Kolesnikova, S. V. (2008). Ispolzovanie matematicheskikh metodov modelirovaniia v issledovanii patoheneza travmaticscheskoi bolezni. Patolojia, 5 (3), 35.
7. Kharchenko, Yu. A. (2014). Adequate assessment of pain is the pledge of successful treatment. Universum: Meditsina i farmakologiiia, 4 (5). Available at: [https://docs.google.com/viewer?url=http://7universum.com/pdf/med/4\(5\)/Kharchenko.pdf](https://docs.google.com/viewer?url=http://7universum.com/pdf/med/4(5)/Kharchenko.pdf)
8. Shostak, N. A., Pravdyuk, N. G. (2016). Pain syndrome: some diagnostic aspects. Clinician, 10 (1), 10–11.
9. Volkovich, O. V., Moldobaeva, N. T. (2007). Unifitsirovannaya otsenka stepeni travmatichnosti operatsii i ee korreliatsii s intensivnostiu posleoperatsyonnoho bolevoho syndroma. Khirurhiia, morfolohiiia, limfolohiiia, 4 (8), 53–55.
10. Stepanova, Ya. V. (2014). Psikhofiziologicheskie aspekty vospriiatija boli v rannem posleoperacionnom periode. Sankt-Peterburg, 155. Available at: <http://www.dslib.net/anestezia/psihofiziologicheskie-aspeky-vosprijatija-boli-v-rannem-posleoperacionnom-periode.html>
11. Peters, M. L., Sommer, M., de Rijke, J. M., Kessels, F., Heinen, E., Patijn, J. et. al. (2007). Somatic and Psychologic Predictors of Long-term Unfavorable Outcome After Surgical Intervention. Annals of Surgery, 245 (3), 487–494. doi: 10.1097/01.sla.0000245495.79781.65
12. Ip, H. Y. V., Abrishami, A., Peng, P. W. H., Wong, J., Chung, F. (2009). Predictors of Postoperative Pain and Analgesic Consumption. Anesthesiology, 111 (3), 657–677. doi: 10.1097/alan.0b013e3181aae87a
13. Yakubovska, S., Vysotska, O., Porvan, A., Yelchaninov, D., Linnyk, E. (2016). Developing a method for prediction of relapsing myocardial infarction based on interpolation diagnostic polynomial. Eastern-European Journal of Enterprise Technologies, 5 (9 (83)), 41–49. doi: 10.15587/1729-4061.2016.81004
14. Vysotskaia, E. V., Svetenko, O. O., Rak, L. I., Porvan, A. P., Svetenko, O. A. (2012). Method for determining systolic myocardial dysfunction in adolescents. Eastern-Eastern-European Journal of Enterprise Technologies, 1 (3 (55)), 27–31. Available at: <http://journals.uran.ua/eejet/article/view/3291/3093>
15. Aivazian, S. A., Eniukov, Y. S., Meshalkin, L. D., Bukhtshtaber, V. M. (2010). Prikladnaya statistika: Klassifikatsii y snizhenie razmernosti. Moscow: Finansy i statistika, 478.
16. Orlov, A. Y. (2004). Matematika sluchaia. Veroiatnost i statistika – osnovnye fakty. Moscow: MZ-Press, 461.
17. Vysotska, O., Dobrorodnina, G., Gordienko, N., Klymenko, V., Chovpan, G., Georgiyants, M. (2016). Studying the mechanisms of formation and development of overweight and obesity for diagnostic information system of obesity. Eastern-European Journal of Enterprise Technologies, 6 (2 (84)), 15–23. doi: 10.15587/1729-4061.2016.85390

**DOI: 10.15587/1729-4061.2017.94961
CLUSTERING METHOD BASED ON FUZZY
BINARY RELATION (p. 10-16)**

Natalia Kondruk

State Higher Education Institution
«Uzhgorod National University», Uzhgorod, Ukraine
ORCID: <http://orcid.org/0000-0002-9277-5131>

Heuristic methods of fuzzy clustering hold a special place in data mining. They are important in preliminary data analysis when the number of clusters, their structure and mutual arrangement are unknown.

The object clustering methods, based on fuzzy binary relations are generalized by developing clear and fuzzy single-level clustering methods, clear and fuzzy sequential multi-level clustering methods. Possible examples of fuzzy binary relations, which characterize similarity of objects by length, angle and distance of their vector features are presented. For this purpose, the Harrington type desirability function and scale, enabling effective analysis of clustering results are suggested.

Based on the proposed methods, the software systems that were effectively used for solving applied clustering problems are developed. Also, the study illustrated the clear single-level clustering method on a specific example.

It is shown that application of the apparatus of fuzzy binary relations in clustering provides an additional opportunity to study the dynamics of the number of clusters, their structure and determine the degree of similarity of objects in a cluster. The results can be used for preliminary data analysis and for holding the object clustering procedure.

Keywords: cluster analysis, automatic object classification, data mining, fuzzy clustering.

References

- Alsmadi, M. K. (2014). A hybrid firefly algorithm with fuzzy-c mean algorithm for MRI brain segmentation. *American Journal of Applied Sciences*, 11 (9), 1676–1691. doi: 10.3844/ajassp.2014.1676.1691
- Giusti, E., Marsili-Libelli, S. (2015). A Fuzzy Decision Support System for irrigation and water conservation in agriculture. *Environmental Modelling & Software*, 63, 73–86. doi: 10.1016/j.envsoft.2014.09.020
- Egrioglu, E., Aladag, C. H., Yolcu, U. (2013). Fuzzy time series forecasting with a novel hybrid approach combining fuzzy c-means and neural networks. *Expert Systems with Applications*, 40 (3), 854–857. doi: 10.1016/j.eswa.2012.05.040
- Son, L. H., Cuong, B. C., Lanzi, P. L., Thong, N. T. (2012). A novel intuitionistic fuzzy clustering method for geo-demographic analysis. *Expert Systems with Applications*, 39 (10), 9848–9859. doi: 10.1016/j.eswa.2012.02.167
- Saha, S., Das, R. (2017). Exploring differential evolution and particle swarm optimization to develop some symmetry-based automatic clustering techniques: application to gene clustering. *Neural Computing and Applications*. doi: 10.1007/s00521-016-2710-0
- Ouadfel, S., Meshoul, S. (2012). Handling Fuzzy Image Clustering with a Modified ABC Algorithm. *International Journal of Intelligent Systems and Applications*, 4 (12), 65–74. doi: 10.5815/ijisa.2012.12.09
- Sahin, R. (2014). Neutrosophic Hierarchical Clustering Algorithms. *Neutrosophic Sets and Systems*, 2, 18–24.
- Abad, M. J. F. H., Derakhshan-Barjoei, P. (2012). Heuristic Model of Cellular Learning Automata for Fuzzy Rule Extraction. *Research Journal of Applied Sciences, Engineering and Technology*, 4 (12), 1701–1707.

- Demin, D. A. (2013). Mathematical modeling in the problem of selecting optimal control of obtaining alloys for machine parts in uncertainty conditions. *Problems of mechanical engineering*, 16 (6), 15–23.
- Shmalyuk, I. Yu., Bushyn, I. M. (2015). Software implementation of the BSP algorithm for clusterization of social networks. *Technology audit and production reserves*, 2 (2 (22)), 21–26. doi: 10.15587/2312-8372.2015.40779
- Kondruk, N. E., Malyar, M. M. (2010). Application of multi-criteria models for the problems of a balanced diet. *Bulletin of Cherkasy State Technological University. Series: Engineering Sciences*, 1, 3–7.
- Kondruk, N. E., Malyar, N. N. (2009). Some applications of clustering criterion space for selection tasks. *Computer Mathematics*, 2, 142–149.
- Kondruk, N. E. (2015). Decision Support Systems for automated diets. *Management of Development of Complex Systems*, 23 (1), 110–114.
- Kondruk, N. E. (2014). Some methods of automatic grouping of objects. *Eastern-European Journal of Enterprise Technologies*, 2 (4 (68)), 20–24. Available at: <http://journals.uran.ua/eejet/article/view/22930/20939>
- Harrington, E. C. (1965). The Desirability Function. *Industrial Quality Control*, 494–498.
- Vyatchenin, D. A. (2004). *Nechetkie metody avtomaticheskoy klassifikacii*. Minsk: UP Tehnoprint, 219.
- Pedrycz, W. (1985). Algorithms of fuzzy clustering with partial supervision. *Pattern Recognition Letters*, 3 (1), 13–20. doi: 10.1016/0167-8655(85)90037-6
- Windham, M. P. (1981). Cluster validity for fuzzy clustering algorithms. *Fuzzy Sets and Systems*, 5 (2), 177–185. doi: 10.1016/0165-0114(81)90015-4
- Tamura, S., Higuchi, S., Tanaka, K. (1971). Pattern Classification Based on Fuzzy Relations. *IEEE Transactions on Systems, Man, and Cybernetics*, SMC-1 (1), 61–66. doi: 10.1109/tsmc.1971.5408605

**DOI: 10.15587/1729-4061.2017.95914
DEVELOPMENT OF A VERIFICATION METHOD
OF ESTIMATED INDICATORS FOR THEIR USE
AS AN OPTIMIZATION CRITERION (p. 17-23)**

Igor Lutsenko

Kremenchuk Mykhailo Ostrohradskyi National University,
Kremenchuk, Ukraine
ORCID: <http://orcid.org/0000-0002-1959-4684>

Elena Fomovskaya

Kremenchuk Mykhailo Ostrohradskyi National University,
Kremenchuk, Ukraine
ORCID: <http://orcid.org/0000-0002-8065-5079>

Iryna Oksanych

Kremenchuk Mykhailo Ostrohradskyi National University,
Kremenchuk, Ukraine
ORCID: <http://orcid.org/0000-0002-4570-711X>

Svetlana Koval

Kremenchuk Mykhailo Ostrohradskyi National University,
Kremenchuk, Ukraine
ORCID: <http://orcid.org/0000-0002-5178-1332>

Olga Serdiuk

Kryvyi Rih National University, Kryvyi Rih, Ukraine
ORCID: <http://orcid.org/0000-0003-0505-0800>

The optimization criterion is that reference point of the controlled systems, which provides the maximum coherence

of the operational process results with the purpose of its owner. Difficulties of solving the tasks, connected with the choice of an adequate optimization criterion are caused by the fact that a large number of indicators intended for use as an optimization criterion have been developed and continue to be developed now.

The verification process of the indicator, which can potentially be used as an optimization criterion, is rather difficult. This difficulty is caused by the fact that the identification process is based on an exclusion method. Those indicators that have shown contradictory results on the classes of operations models identified by the rating efficiency should be excluded from the "contenders".

During the researches, the hypothesis on the possibility of creating the reference models, allowing the development of direct verification methods wasn't confirmed. However, the comparative research of cybernetic models of operations with different duration for consistency has allowed setting a restriction on the formation rules of models of this class and defining the rules of their equivalent converting.

Besides, during the researches, the method of creating a class of simple operation models with the predetermined identification, concerning their rating efficiency, has been developed. This means that the rating creation of these models doesn't require determination of local efficiency criteria.

Creation of a new class of reference models expands the possibilities of the estimated indicator verification method. At the same time, the positive effect of expansion of the opportunities of the verification method is shown not so much in an increase in the probability of excluding the inadequate estimated indicator, but in the introduction of a restriction on the rules of creating the classes of reference operation models.

Introduction of a restriction prevents the possibility of excluding the adequate estimated indicator from consideration.

Keywords: local efficiency criterion, estimated indicators verification method, optimization criterion.

References

1. Lutsenko, I., Vihrova, E., Fomovskaya, E., Serdiuk, O. (2016). Development of the method for testing of efficiency criterion of models of simple target operations. Eastern-European Journal of Enterprise Technologies, 2 (4 (80)), 42–50. doi: 10.15587/1729-4061.2016.66307
2. Lutsenko, I., Fomovskaya, E., Oksanych, I., Vikhrova, E., Serdiuk, O. (2017). Formal signs determination of efficiency assessment indicators for the operation with the distributed parameters. Eastern-European Journal of Enterprise Technologies, 1 (4 (85)), 24–30. doi: 10.15587/1729-4061.2017.91025
3. Gorbatyuk, S. M., Shapoval, A. A., Mos'pan, D. V., Dragobetskii, V. V. (2016). Production of periodic bars by vibrational drawing. Steel in Translation, 46 (7), 474–478. doi: 10.3103/s096709121607007x
4. Anishchenko, U. V., Kryuchkov, A. N., Kul'bak, L. I., Martinovich, T. S. (2008). Optimization of the structure of multifunctional information systems according to the criterion of a required value of the efficiency ratio. Automatic Control and Computer Sciences, 42 (4), 203–209. doi: 10.3103/s0146411608040068
5. Miskowicz, M. (2010). Efficiency of Event-Based Sampling According to Error Energy Criterion. Sensors, 10 (3), 2242–2261. doi: 10.3390/s100302242
6. Xu, Q., Wehrle, E., Baier, H. (2012). Adaptive surrogate-based design optimization with expected improvement used as infill criterion. Optimization, 61 (6), 661–684. doi: 10.1080/02331934.2011.644286
7. Xia, L. (2016). Optimization of Markov decision processes under the variance criterion. Automatica, 73, 269–278. doi: 10.1016/j.automatica.2016.06.018
8. Shapoval, A. A., Mos'pan, D. V., Dragobetskii, V. V. (2016). Ensuring High Performance Characteristics For Explosion-Welded Bimetals. Metallurgist, 60 (3-4), 313–317. doi: 10.1007/s11015-016-0292-9
9. Vasilyev, E. S. (2013). Optimization of the architecture of a charge pump device on the basis of the energy efficiency criterion. Journal of Communications Technology and Electronics, 58 (1), 95–99. doi: 10.1134/s1064226913010099
10. Shorikov, A. F., Rassadina, E. S. (2010). Multi-criterion optimization of production range generation by an enterprise. Economy of Region, 2, 189–196. doi: 10.17059/2010-2-18
11. Dragobetskii, V. V., Shapoval, A. A., Mos'pan, D. V., Trotsko, O. V., Lotous, V. V. (2015). Excavator bucket teeth strengthening using a plastic explosive deformation. Metallurgical and Mining Industry, 4, 363–368.
12. Mansour, M. R., Delbem, A. C. B., Alberto, L. F. C., Ramos, R. A. (2015). Integrating Hierarchical Clustering and Pareto-Efficiency to Preventive Controls Selection in Voltage Stability Assessment. Evolutionary Multi-Criterion Optimization, 487–497. doi: 10.1007/978-3-319-15892-1_33
13. Harchenko, V. P., Babejchuk, D. G., Slyunyaev, O. S. (2009). Optimization of network information air navigation facilities by the generalized criterion of efficiency. Proceedings of National Aviation University, 38 (1), 3–5. doi: 10.18372/2306-1472.38.1650
14. Yang, Q., Xu, J., Cao, B., Li, X.; Xu, J. (Ed.) (2017). A simplified fractional order impedance model and parameter identification method for lithium-ion batteries. PLOS ONE, 12 (2), e0172424. doi: 10.1371/journal.pone.0172424
15. Malkov, M. V., Malyigina, S. N. (2010). Petri Nets and Modeling. Trudy Kolskogo nauchnogo tsentra RAN, 3, 35–40.
16. Lutsenko, I. (2015). Identification of target system operations. Development of global efficiency criterion of target operations. Eastern-European Journal of Enterprise Technologies, 2 (2 (74)), 35–40. doi: 10.15587/1729-4061.2015.38963

DOI: 10.15587/1729-4061.2017.95870

OPTIMIZATION OF KNOWLEDGE BASES ON THE BASIS OF FUZZY RELATIONS BY THE CRITERIA “ACCURACY – COMPLEXITY” (p. 24-31)

Hanna Raktyanska

Vinnytsia National Technical University, Vinnytsia, Ukraine
ORCID: <http://orcid.org/0000-0001-5863-3730>

The method of optimization of fuzzy classification knowledge bases by the criteria “inference accuracy – complexity” was proposed. A relational fuzzy model, which corresponds to the fuzzy classification knowledge base, was developed. The matrix of fuzzy relations in the form of one-dimensional projection “input terms – output classes” is a simplified representation of the system of classification rules. A problem on the optimization of a knowledge base is reduced to the problem on the min-max clustering and comes down to selecting such partition matrices “inputs – output” that provide for the required or extreme levels of inference accuracy and the number of rules.

In the relational models, a question about optimal choice of the number of output terms remains open. A selection of output classes, input terms and rules is reduced to the problem on discrete optimization of the algorithm reliability indicators, in order to solve which, we employed the gradient method. The number and location of hyperboxes are determined by the relations matrix, and the sizes of hyperboxes are defined as a result

of tuning of the triangular membership functions. A selection of the number of input and output terms in the partition matrices may be performed both under the offline mode and by adaptive adding/removing of terms.

Known methods of the min-max clustering apply heuristic procedures for the selection of the number of rules (classes). The proposed method generates variants of fuzzy knowledge bases in accordance with the formalized procedures of reliability analysis and synthesis of algorithmic processes. This resolves a general problem on the methods of min-max clustering related to the minimization of the number of input terms without losing inference accuracy.

A transition to the relational fuzzy model provides simplification of the process of the knowledge bases tuning both for the assigned and unknown output classes.

Keywords: optimization of fuzzy knowledge bases, min-max clustering, fuzzy relational models.

References

1. Yager, R., Filev, D. (1994). Essentials of fuzzy modeling and control. New York: John Wiley & Sons, 408.
2. Rotshtein, A. P., Rakytyanska, H. B. (2012). Fuzzy Evidence in Identification, Forecasting and Diagnosis. Heidelberg: Springer, 314. doi: 10.1007/978-3-642-25786-5
3. Mandal, S., Jayaram, B. (2015). SISO fuzzy relational inference systems based on fuzzy implications are universal approximators. *Fuzzy Sets and Systems*, 277, 1–21. doi: 10.1016/j.fss.2014.10.003
4. Scherer, R. (2012). Relational Modular Fuzzy Systems. Studies in Fuzziness and Soft Computing. Springer Berlin Heidelberg, 39–50. doi: 10.1007/978-3-642-30604-4_4
5. Gonzalez, A., Perez, R., Caises, Y., Leyva, E. (2012). An Efficient Inductive Genetic Learning Algorithm for Fuzzy Relational Rules. *International Journal of Computational Intelligence Systems*, 5 (2), 212–230. doi: 10.1080/18756891.2012.685265
6. Graves, D., Noppen, J., Pedrycz, W. (2012). Clustering with proximity knowledge and relational knowledge. *Pattern Recognition*, 45 (7), 2633–2644. doi: 10.1016/j.patcog.2011.12.019
7. De Carvalho, F. de A. T., Lechevallier, Y., de Melo, F. M. (2013). Relational partitioning fuzzy clustering algorithms based on multiple dissimilarity matrices. *Fuzzy Sets and Systems*, 215, 1–28. doi: 10.1016/j.fss.2012.09.011
8. Bargiela, A., Pedrycz, W. (2013). Optimised Information Abstraction in Granular Min/Max Clustering. *Smart Innovation, Systems and Technologies*, 31–48. doi: 10.1007/978-3-642-28699-5_3
9. Gaspar, P., Carbonell, J., Oliveira, J. L. (2012). Parameter Influence in Genetic Algorithm Optimization of Support Vector Machines. *Advances in Intelligent and Soft Computing*, 43–51. doi: 10.1007/978-3-642-28839-5_5
10. Wu, Z., Zhang, H., Liu, J. (2014). A fuzzy support vector machine algorithm for classification based on a novel PIM fuzzy clustering method. *Neurocomputing*, 125, 119–124. doi: 10.1016/j.neucom.2012.07.049
11. Mohammed, M. F. Lim, C. P. (2017). Improving the Fuzzy Min-Max neural network with a K-nearest hyperbox expansion rule for pattern classification. *Applied Soft Computing*, 52, 135–145. doi: 10.1016/j.asoc.2016.12.001
12. Seera, M., Lim, C. P., Loo, C. K., Singh, H. (2015). A modified fuzzy min-max neural network for data clustering and its application to power quality monitoring. *Applied Soft Computing*, 28, 19–29. doi: 10.1016/j.asoc.2014.09.050
13. Reyes-Galaviz, O. F., Pedrycz, W. (2015). Granular fuzzy modeling with evolving hyperboxes in multi-dimensional space of numerical data. *Neurocomputing*, 168, 240–253. doi: 10.1016/j.neucom.2015.05.102
14. Rotshtein, A. P., Rakytyanska, H. B. (2014). Optimal Design of Rule-Based Systems by Solving Fuzzy Relational Equations. *Studies in Computational Intelligence*, 167–178. doi: 10.1007/978-3-319-06883-1_14
15. Rakytyanska, H. (2015). Optimization of composite fuzzy knowledge bases on rules and relations. *Inf. Technol. Comput. Eng.*, 1, 17–26.
16. Rakytyanska, H. (2015). Fuzzy classification knowledge base construction based on trend rules and inverse inference. *Eastern-European Journal of Enterprise Technologies*, 1 (3 (73)), 25–32. doi: 10.15587/1729-4061.2015.36934
17. Rotshtein, A. P., Rakytyanska, H. B. (2012). Fuzzy Genetic Object Identification: Multiple Inputs/Multiple Outputs Case. *Advances in Intelligent and Soft Computing*, 375–394. doi: 10.1007/978-3-642-23172-8_25

DOI: 10.15587/1729-4061.2017.97144

FINDING THE PROBABILITY DISTRIBUTION OF STATES IN THE FUZZY MARKOV SYSTEMS (p. 32-38)

Lev Raskin

National Technical University
«Kharkiv Polytechnic Institute», Kharkiv, Ukraine
ORCID: <http://orcid.org/0000-0002-9015-4016>

Oksana Sira

National Technical University
«Kharkiv Polytechnic Institute», Kharkiv, Ukraine
ORCID: <http://orcid.org/0000-0002-4869-2371>

Tetiana Katkova

Berdyansk University of Management and Business, Berdyansk, Ukraine
ORCID: <http://orcid.org/0000-0002-1051-4262>

A problem on finding the stationary distributions of probabilities of states for the Markov systems under conditions of uncertainty is solved. It is assumed that parameters of the analyzed Markov and semi-Markov systems (matrix of transition intensities, analytical description of distribution functions of the durations of being in states of the system before exiting, as well as a matrix of transition probabilities) are not clearly assigned. In order to describe the fuzziness, we employ the Gaussian membership functions, as well as functions of the (L–R) type. The appropriate procedure of systems analysis is based on the developed technology for solving the systems of linear algebraic equations with fuzzy coefficients. In the problem on analysis of a semi-Markov system, the estimation of components of the stationary distribution of probabilities of states of the system is obtained by the minimization of a complex criterion. The criterion considers the measure of deviation of the desired distribution from the modal one, as well as the level of compactness of membership functions of the fuzzy result of solution. In this case, we apply the rule introduced for the calculation of expected value of fuzzy numbers. The criterion proposed is modified through the introduction of weight coefficients, which consider possible differences in the levels of requirements to different components of the criterion.

Keywords: Markov and semi-Markov systems, complex criterion, deviation of solution from the modal one, compactness measure of solution.

References

1. Bertalanfy, L. (1969). Obshchaia teoriia system. Moscow: Progress, 82.

2. Mesarovich, M., Takakhara, Ya. (1978). *Obshchaia teoriya system: matematicheskie osnovy*. Moscow: MYR, 283.
3. Volkova, V. N. (2006). *Teoriya system*. Moscow: Vysshiaia shkola, 511.
4. Raskin, L. G. (1976). *Analyz slozhnykh sistem i elementy teorii upravleniya*. Moscow: Sov. radyo, 344.
5. Raskin, L. G. (1988). *Matematicheskie metody yssledovaniia operatsyi y analiza slozhnykh sistem vooruzheniya PVO*. Kharkiv: VYRTA, 177.
6. Zadeh, L. A. (1965). Fuzzy sets. *Information and Control*, 8 (3), 338–353. doi: 10.1016/s0019-9958(65)90241-x
7. Kofman, A. (1982). *Vvedenie v teoriyu nechetkykh mnozhestv*. Moscow: Radyo y sviaz, 486.
8. Nehrutse, K. (1981). *Prymenenie teorii system k problemam upravleniya*. Moscow: MYR, 219.
9. Orlovskyi, S. A. (1981). *Problemy pryniatia reshenyi pry nechetkoi ynformatsyy*. Moscow: Nauka, 264.
10. Zaichenko, Yu. P. (1991). *Yssledovanye operatsyi. Nechetkaia optymyzatsiya*. Kyiv: Vyshchaia shkola, 191.
11. Kaufman, A., Gupta, M. (1985). *Introduction to Fuzzy Arithmetic: Theory and Applications*. New York, 351.
12. Raskin, L. G., Sira, O. V. (2008). *Nechetkaia matematyka*. Kharkiv: Parus, 352.
13. Tykhonov, V. Y., Myronov, M. A. (1977). *Markovskye protsessy*. Moscow: Sov. Radyo, 483.
14. Koroliuk, V. S., Turbin, A. F. (1976). *Polimarkovskye protsessy i ih prilozheniya*. Kyiv: Naukova dumka, 182.
15. Koks, D. R., Smyt, V. D. (1967). *Teoriya vosstanovleniya*. Moscow: Sov. radyo, 299.
16. Fakoor, M., Kosari, A., Jafarzadeh, M. (2016). Humanoid robot path planning with fuzzy Markov decision processes. *Journal of Applied Research and Technology*, 14 (5), 300–310. doi: 10.1016/j.jart.2016.06.006
17. Cheng, J., Park, J. H., Liu, Y., Liu, Z., Tang, L. (2017). Finite-time H_∞ fuzzy control of nonlinear Markovian jump delayed systems with partly uncertain transition descriptions. *Fuzzy Sets and Systems*, 314, 99–115. doi: 10.1016/j.fss.2016.06.007
18. Sira, O. V., Al-Shqeerat, K. H. (2009). A New Approach for Resolving Equations with Fuzzy Parameters. *European Journal of Scientific Research*, 38 (4), 619–625.
19. Raskin, L., Sira, O. (2016). Method of solving fuzzy problems of mathematical programming. *Eastern-European Journal of Enterprise Technologies*, 5 (4 (83)), 23–28. doi: 10.15587/1729-4061.2016.81292
20. Raskin, L. G., Kyrychenko, Y. O., Sira, O. V. (2013). *Prykladnoe kontynualnoe lyneinoe prohrammyrovanye*. Kharkiv, 293.
21. Kostenko, Yu. T., Raskin, L. G. (1996). *Prohnozyrovanye tekhnicheskoho sostoianiya sistem upravleniya*. Kharkiv: Osnova, 303.
22. Pawlak, Z. (1982). Rough sets. *International Journal of Computer & Information Sciences*, 11 (5), 341–356. doi: 10.1007/bf01001956
23. Raskin, L., Sira, O. (2016). Fuzzy models of rough mathematics. *Eastern-European Journal of Enterprise Technologies*, 6 (4 (84)), 53–60. doi: 10.15587/1729-4061.2016.86739

DOI: 10.15587/1729-4061.2017.95783

RECURRENT TRANSFORMATION OF THE DYNAMICS MODEL FOR AUTONOMOUS UNDERWATER VEHICLE IN THE INERTIAL COORDINATE SYSTEM (p. 39-47)

Alexander Trunov

Petro Mohyla Black Sea National University, Mykolaiv, Ukraine
ORCID: <http://orcid.org/0000-0002-8524-7840>

We considered the motion equation for an autonomous underwater vehicle (AUV) with a manipulator onboard in the inertial coordinate system (ICS). A nonlinear system of differential equations takes into account in the form of attached mass coefficients the impact of infiltration effects and dissymmetry of the outer shell of the body. The work of manipulator and fixing elements is accounted for by additional forces and moments that occur as a consequence of their relative motion. The expressions of forces and moments are presented for the given kinematic schemes. A recurrent approximation method is applied, as result of which we transformed a solution for the system of nonlinear differential equations to the recurrent sequence of analytical expressions. The constructed sequence describes the dynamics of AUV with regard to the angular position and kinematic parameters without simplifications in the kinematic matrix. The algorithm that was synthesized based on this model is presented, which provides for presenting, in the form of recurrent sequence of actions and calculations, the expressions for analytical representation of solution for the direct problem on the AUV dynamics. Based on the analytical approximations of the model, we present expressions for an error that occurs as a consequence of angular deviations and simplifications in the kinematic matrices.

The dynamics of AUV was modeled and quantitative values of error were obtained as a function of operating and kinematic parameters of AUV in ICS. The derived models of dynamics and expressions for errors are important for decision support systems because they allow the representation of information about the motion of AUV and manipulator aboard in a uniform ICS. The possibilities obtained have eliminated obstacles to comprehensive modeling of technological AUV and creation of ACS. Using the results of modeling the impact of manipulator's work aboard AUV, we established factors that influence the magnitude of error when calculating by the simplified kinematic matrices.

Keywords: autonomous underwater vehicle, inertial coordinate system, recurrent sequence, kinematic matrix.

References

1. Blintsov, V. S. (1998). *Pryvy'azni pidvodni systemy*. Kyiv: Naukova Dumka, 231.
2. Blintsov, V. S. (2010). *Keruvannya prostorovym rukhom pidvodnogo aparata z urakhuvanniam vzayemozv'yazkiv mizh skladovym rukhu po riznym osyam koordynat*. Innovatsiyi v sudnobuduvanni ta okeanotekhnitsi. Mykolaiv: NUK, 406–408.
3. Byelousov, I. (2013). Suchasni i perspektivni nezaseleni pidvodni aparaty VMS SShA. *Zakordonnyy viys'kovyy ohlyad*, 5, 79–88.
4. Bocharov, L. (2009). *Nezaseleni pidvodni aparaty: Stan i zahal'ni tendentsiyi rozvytku*. Elektronika: Nauka, Tekhnolohiya, Biznes, 7, 62–69.
5. Lukomskij, Yu. A., Chugunov, V. S. (1988). *Sistemy upravleniya morskimi podvizhnymi ob'ektami*. Leningrad: izd. Sudostroenie, 272.
6. Slizhevskij N. B. (1998). *Hodkost' i upravlyaemost' podvodnyh tekhnicheskikh sredstv*. Nikolaev, 148.
7. FDS3 (Forward Deployed Side Scan Sonar) Jane's International Defense Review. Available at: <http://www.janes.com>
8. Bremer, R. H., Cleophas, P. L. H., Fitski, H. J., Keus, D. (2007). TNO report. Unmanned surface and underwater vehicles. Netherlands, 126.
9. Bohuslav's'kyy, A. B., Lokhin, V. M., Man'ko, S. V. (1995). *Formuvannya znan' dlya planuvannya rukhiv robotiv v seredovishchi z pereshkodamy na osnovi tekhnolohiyi ekspertnykh system*. Shtuchnyy intelekt v systemakh avtomatychnoho keruvannya. Kyiv. Concept Ltd, 12–23.

10. Trunov, O. M. (2007). Dynamika avariyno-ryatuval'noho aparatu v umovakh rehulyarnoho khvylyuvannya i shkvaliv. Zbirnyk naukovykh prats', NUK, 6, 30–41.
11. Fossen, T. I. (2011). Handbook of Marine Craft Hydrodynamics and Motion Control. Wiley, 575. doi: 10.1002/9781119994138
12. From, P. J., Gravdahl, J. T., Pettersen, K. Y. (2014). Vehicle-Manipulator Systems. Springer London, 388. doi: 10.1007/978-1-4471-5463-1
13. Han, J., Chung, W. K. (2007). Redundancy resolution for underwater vehicle-manipulator systems with minimizing restoring moments. 2007 IEEE/RSJ International Conference on Intelligent Robots and Systems. doi: 10.1109/iros.2007.4399292
14. McMillan, S., Orin, D. E., McGhee, R. B. (1995). Efficient dynamic simulation of an underwater vehicle with a robotic manipulator. IEEE Transactions on Systems, Man, and Cybernetics, 25 (8), 1194–1206. doi: 10.1109/21.398681
15. Rusu, R. B., Cousins, S. (2011). 3D is here: Point Cloud Library (PCL). 2011 IEEE International Conference on Robotics and Automation. doi: 10.1109/icra.2011.5980567
16. Trunov, A. (2016). Realization of Paradigm of Prescribed Control of Nonlinear as the Maximization Adequacy Problem. Eastern-European Journal of Enterprise Technologies, 4 (4 (82)), 50–58. doi: 10.15587/1729-4061.2016.75674
17. Trunov, A. (2016). Criteria for the evaluation of model's error for a hybrid architecture DSS in the underwater technology ACS. Eastern-European Journal of Enterprise Technologies, 6 (9 (84)), 55–62. doi: 10.15587/1729-4061.2016.85585
18. Trunov, A. N. (2012). Recurrence approximation in problems of modeling and design. Mykolaiv, 270.
19. Lendyuk, T., Sachenko, S., Rippa, S., Sapojnyk, G. (2015). Fuzzy rules for tests complexity changing for individual learning path construction. 2015 IEEE 8th International Conference on Intelligent Data Acquisition and Advanced Computing Systems: Technology and Applications (IDAACS). doi: 10.1109/idaacs.2015.7341443
20. Fisun, M., Shved, A., Nezdioli, Y., Davydenko, Y. (2015). The experience in application of information technologies for teaching of disabled students. 2015 IEEE 8th International Conference on Intelligent Data Acquisition and Advanced Computing Systems: Technology and Applications (IDAACS). doi: 10.1109/idaacs.2015.7341441
21. Kondratenko, Y. P., Sidenko, I. V. (2014). Decision-Making Based on Fuzzy Estimation of Quality Level for Cargo Delivery. Studies in Fuzziness and Soft Computing, 331–344. doi: 10.1007/978-3-319-06323-2_21
22. Kondratenko, Y. P., Gerasin, O. S., Topalov, A. M. (2015). Modern sensing systems of intelligent robots based on multi-component slip displacement sensors. 2015 IEEE 8th International Conference on Intelligent Data Acquisition and Advanced Computing Systems: Technology and Applications (IDAACS). doi: 10.1109/idaacs.2015.7341434
23. Nykorak, A., Hiromoto, R. E., Sachenko, A., Koval, V. (2015). A wireless navigation system with no external positions. 2015 IEEE 8th International Conference on Intelligent Data Acquisition and Advanced Computing Systems: Technology and Applications (IDAACS). doi: 10.1109/idaacs.2015.7341433
24. Dyda, A. A., Oskin, D. A., Artemiev, A. V. (2015). Robot dynamics identification via neural network. 2015 IEEE 8th International Conference on Intelligent Data Acquisition and Advanced Computing Systems: Technology and Applications (IDAACS). doi: 10.1109/idaacs.2015.7341437
25. Trunov, O. M. (2014). Methodology of evaluation alternatives on the basis several etalons. Naukovi pratsi: Naukovo-metodychnyy zhurnal. Komp'yuterni tekhnolohiyi, 237 (225), 99–104.
26. Trunov, O. M., Belikov, O. E. (2015). Modeling of interaction EMW with biologics objects in during phototherapy. Sience and methodology journal, 94, 23–27.
27. Trunov, O. M., Novosadovskiy, O. O., Kikhtenko, D. P. (2014). Improving the mathematical model of the dynamics for underwater vehicles with asymmetrical hulls. Naukovi pratsi: Naukovo-metodychnyy zhurnal. Komp'yuterni tekhnolohiyi, 237 (225), 90–98.
28. Yastrebov, V. S., Garbus, E. I., Filatov, A. M., Blincov, V. S., Ivanishin, B. P., Trunov, A. N., Pavlov, A. P. (1990). Razrabotka i ispytanie adaptivnogo podvodnogo robita. Sb. nauchnyh trudov instituta Okeanologii im. P. P. Shirshova AN SSSR. Moscow, 98–112.

DOI: 10.15587/1729-4061.2017.95764

DEVELOPMENT OF PROJECTION TECHNIQUE FOR DETERMINING THE NON-CHAOTIC OSCILLATION TRAJECTORIES IN THE CONSERVATIVE PENDULUM SYSTEMS (p. 48-57)

Oleg Semkiv

National University of

Civil Defense of Ukraine, Kharkiv, Ukraine

ORCID: <http://orcid.org/0000-0002-9347-0997>

Olga Shoman

National Technical University

“Kharkiv Polytechnic Institute”, Kharkiv, Ukraine

ORCID: <http://orcid.org/0000-0002-3660-0441>

Elena Sukharkova

Ukrainian State University of

Railway Transport, Kharkiv, Ukraine

ORCID: <http://orcid.org/0000-0003-1033-4728>

Alla Zhurilo

National Technical University

“Kharkiv Polytechnic Institute”, Kharkiv, Ukraine

ORCID: <http://orcid.org/0000-0003-4084-4622>

Hanna Fedchenko

National Technical University

“Kharkiv Polytechnic Institute”, Kharkiv, Ukraine

ORCID: <http://orcid.org/0000-0003-0690-6017>

We developed a technique to determine the non-chaotic oscillations of loads in the conservative pendulum systems by using the graphic technology of projection focusing. In this case, phase trajectories of the differential equations of oscillation are considered as projections of integral curves from the phase space onto the phase plane. The effect exerted by the value of one of the system's parameters on the image of phase trajectories was examined (at stable values of other parameters). By using projection focusing, the element that defines the critical value of variable parameter is selected among a family of phase trajectories, which, in a combination with other parameters, allows us to describe a non-chaotic trajectory in the load motion.

The need for such studies is predetermined by the absence, in practice, of an engineering method for computing the non-chaotic trajectory of the load motion for a certain pendulum system.

We proposed the notion of a focus-line of the parametric family of curves and the technique of projection focusing, which is based on it. We constructed integral curves in the phase space based on the numerical solution of second order Lagrange differential equations. A procedure is presented to determine the critical value of pendulum oscillation parameter by using the graphic notion of projection focusing of phase trajectories in the

solutions of second order Lagrange differential equations. The examples are presented of determining the parameters of certain pendulums, which would provide for the non-chaotic trajectory of the load oscillations.

The developed computerized projection technique for the simulation of oscillations in the pendulum mechanical systems makes it possible to choose the required values of parameters and initial conditions for initiating the oscillations, which provide for the non-chaotic technological character of oscillation trajectory of their elements, which is important for the practical implementation in the designs of pendulum systems.

Keywords: pendulum systems, conservative systems, integral curves, phase trajectories, projection focusing.

References

1. Nedel'ko, N. S. (2010). Ispol'zovanie teorii katastrof k analizu povedeniya ekonomiceskikh system. Vestnik MGTU, 13 (1), 223–227.
2. Ostrejkovskij, V. A. (2005). Analiz ustojchivosti i upravlyayemosti dinamicheskikh sistem metodami teorii katastrof. Moscow: Vyssh. shk., 326.
3. Gavin, H. P. (2016). Generalized Coordinates, Lagrange's Equations, and Constraints. Structural Dynamics, 1–23.
4. Klimenko, A. A., Mihlin, Yu. V. (2009). Nelinejnaya dinamika pruzhinnogo mayatnika. Nelinejnaya mekhanika, 27, 51–65.
5. Malineckij, G. G., Potapov, A. B., Podlazov, A. V. (2006). Nelinejnaya dinamika: podhody, rezul'taty, nadezhdy. Moscow: URSS, 280.
6. Kecik, K. (2015). Dynamics and control of an active pendulum system. International Journal of Non-Linear Mechanics, 70, 63–72. doi: 10.1016/j.ijnonlinmec.2014.11.028
7. Ding, F., Huang, J., Wang, Y., Matsuno, T., Fukuda, T., Sekiyama, K. (2010). Modeling and control of a novel narrow vehicle. 2010 IEEE International Conference on Robotics and Biomimetics. doi: 10.1109/robio.2010.5723487
8. Butterworth, J. A., Pao, L. Y., Abramovitch, D. Y. (2008). The effect of nonminimum-phase zero locations on the performance of feedforward model-inverse control techniques in discrete-time systems. 2008 American Control Conference. doi: 10.1109/acc.2008.4586900
9. Butikov, E. I. (2010). Stabilizaciya perevernutogo mayatnika (60 let mayatniku Kapicy). Komp'yuternye instrumenty v obrazovanii, 5, 39–51.
10. Shironosov, V. G. (2000). Rezonans v fizike, himii i biologii. Izhevsk: Udmurtskij universitet, 92.
11. Yehia, H. M. (2006). On the integrability of the motion of a heavy particle on a tilted cone and the swinging Atwood machine. Mechanics Research Communications, 33 (5), 711–716. doi: 10.1016/j.mechrescom.2005.06.015
12. Tufillaro, N. B., Abbott, T. A., Griffiths, D. J. (1984). Swinging Atwood's Machine. American Journal of Physics, 52 (10), 895–903. doi: 10.1119/1.13791
13. Manzhaev, P. V., Levin, V. E. (2015). Issledovanie bol'shih kolebanij dvojnogo matematicheskogo mayatnika. Trudy XVI Vserossijskoj nauchno-tehnicheskoy konferencii „Nauka. Pro-myshlennost'. Oborona". Novosibirsk, 526–530.
14. Semkiv, O. M. (2016). Hrafichnyy komp'yuternyy sposib vyznachennya nekhaotichnykh trayektoriy kolyvan' mayatnykovykh system. Vestnyk Khar'kovskoho nats. avtomobyl'no-dorozhnoho unyversyteta, 72, 94–101.
15. Girsh, A. G. (2013). Kompleksnaya geometriya – evklidova i psevdoevlidova. Moscow: Maska, 216.
16. Stepanenko, O. S. (2006). Rabota na PK v ofise. Moscow: Vil'yams, 768.
17. Kutsenko, L. M., Semkiv, O. M. (2016). Doslidzhennya initsiyuvannya rukhu vizka za dopomohoyu kolyvannya 2d-pruzhynnoho mayatnyka. Suchasni problemy modelyuvannya, 6, 71–76.
18. Vishenkova, E. A., Holostova, O. V. (2012). K dinamike dvojnoho mayatnika s horizontal'n'o vibriruyushchej tochkoj podvesa. Vestnik Udmurtskogo universiteta. Matematika. Mekhanika, 2, 114–129.
19. Nalavade, M. R., Bhagat, M. J., Patil, V. V. (2014). Balancing Double Inverted Pendulum on A cart by Linearization Technique. International Journal of Recent Technology and Engineering (IJRTE), 3 (1), 153–157.

DOI: 10.15587/1729-4061.2017.99273

CONSTRUCTION OF A NUMERICAL METHOD FOR FINDING THE ZEROS OF BOTH SMOOTH AND NONSMOOTH FUNCTIONS (p. 58-64)

Roman Bihun

Ivan Franko National University of Lviv, Lviv, Ukraine
ORCID: <http://orcid.org/0000-0003-4363-4532>

Gregoriy Tsehelyk

Ivan Franko National University of Lviv, Lviv, Ukraine
ORCID: <http://orcid.org/0000-0002-5826-0628>

Here we report building a numerical method for finding the zeros of a function of one real variable using the apparatus of nonclassical Newton's minorants and diagrams of functions', given in the tabular form. The examples of the search for zeros of functions are given.

A problem on finding the roots of equations belongs to important problems of applied mathematics. Classical methods of finding the zeroes of functions require first to isolate the roots and then to find them. In order to find a separate root with a given accuracy, it is necessary to choose one of the points in the vicinity that contains the root as the initial approximation and to employ an appropriate iterative process.

The numerical method constructed does not require additional information about the location of roots and has many advantages over other methods for finding the zeros of functions, in particular: simplicity and visual representation of the method. Because of this, it can gain a widespread application in many areas, such as physics, mechanics, and natural sciences. By using the method built, it is possible to find the roots in a linear time, which is rather fast. The practical value of a numerical method is largely determined by the speed of obtaining the solution.

Keywords: minorant of a function, zero of a function, Chebyshev polynomial, Newton's diagram, smooth and nonsmooth function.

References

1. Berezin, Y., Zhydkov, N. (1996). Metody vychyslenyi. Vol. 1. Moscow: Nauka, 464.
2. Tsigaridas, E. P., Emiris, I. Z. (2006). Univariate Polynomial Real Root Isolation: Continued Fractions Revisited. Lecture Notes in Computer Science, 817–828. doi: 10.1007/11841036_72
3. Suli, E., Mayers, D. F. (2003). An Introduction to Numerical Analysis. Cambridge University Press, 435. doi: 10.1017/cbo9780511801181
4. Grau, M., Diaz-Barrero, J. L. (2006). An improvement to Ostrowski root-finding method. Applied Mathematics and Computation, 173 (1), 450–456. doi: 10.1016/j.amc.2005.04.043
5. Abdelhafid, S. (2016). A fourth order method for finding a simple root of univariate function. Boletim da Sociedade Paranaense de Matematica, 34 (2), 197. doi: 10.5269/bspm.v34i2.24763

6. Ozyapici, A., Sensoy, Z. B., Karanfiller, T. (2016). Effective Root-Finding Methods for Nonlinear Equations Based on Multiplicative Calculi. *Journal of Mathematics*, 2016, 1–7. doi: 10.1155/2016/8174610
7. Chen, X.-D., Shi, J., Ma, W. (2017). A fast and robust method for computing real roots of nonlinear equations. *Applied Mathematics Letters*, 68, 27–32. doi: 10.1016/j.aml.2016.12.013
8. Tsehelyk, G. (2013). Aparat neklasychnykh mazhorant i diafram Niutona funktsii, zadanykh tablychno, ta yoho vykorystannia v chyselnomu analizi. Lviv: LNU imeni Ivana Franka, 190.
9. Bihun, R. R., Tsehelyk, G. G. (2014). Device of non-classical Newton's minorant of functions of two real table-like variables and its application in numerical analysis. *International Journal of Information and Communication Technology Research*, 4 (7), 284–287.
10. Bihun, R. R., Tsehelyk, G. G. (2015). Numerical Method for Finding All Points of Extremum of Random as Smooth and Non-Smooth Functions of One Variable. *Global Journal of Science Frontier Research: F Mathematics and Decision Sciences*, 15 (2), 87–93.
11. Kostovskyi, A. (1967). Lokalyzatsiya po moduliam nulei riada Lorana y eho proyzvodnykh. Lviv, 208.
12. Kardash, A. I., Chulyk, I. I. (1972). Doslidzhennia hranychnykh vlastivostei mazhoranty i diafram Niutona funktsii dvokh kompleksnykh zminnykh. Dop. AN URSR. Ser. A, 4, 316–319.
13. Kardash, A. I., Chulyk, I. I. (1972). Ob oblasti skhodimosti riada Dyrykhle funktsyy dvukh kompleksnykh perevremenennykh y eho mazhoranty Niutona. Dokl. AN SSSR. Ser. A, 206 (4), 804–807.
14. Kardash, A. I., Chulyk, I. I. (1972). Doslidzhennia hranytsi oblasti zbizhnosti stepenevykh riadiv funktsii dvokh kompleksnykh zminnykh. Dop. AN URSR. Ser. A, 5, 411–414.